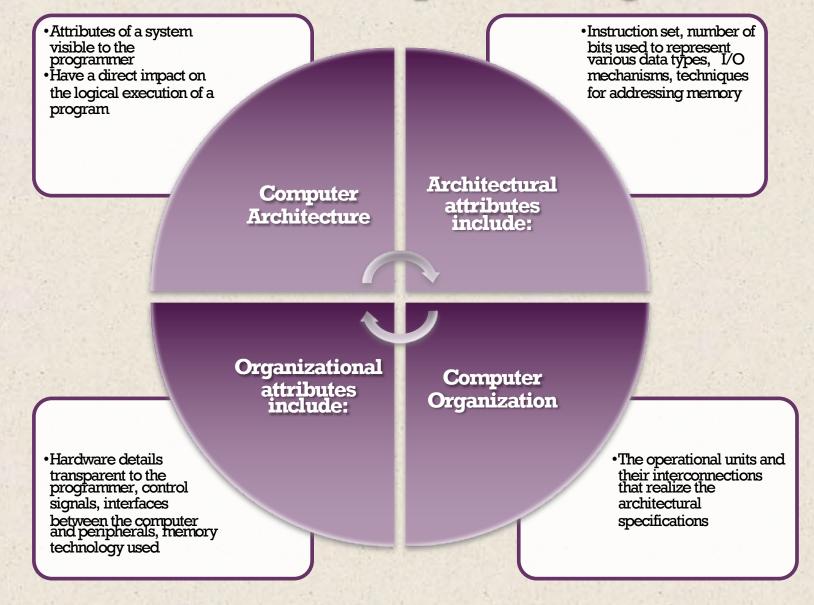


William Stallings Computer Organization and Architecture 10th Edition

Chapter l Basic Concepts and Computer Evolution

Computer Architecture

Computer Organization



IBM System 370 Architecture

IBM System/370 architecture

- Was introduced in 1970
- Included a number of models
- Could upgrade to a more expensive, faster model without having to abandon original software
- New models are introduced with improved technology, but retain the same architecture so that the customer's software investment is protected
- Architecture has survived to this day as the architecture of IBM's mainframe product line



Structure and Function

Hierarchical system

- Set of interrelated subsystems
- Hierarchical nature of complex systems is essential to both their design and their description
- Designer need only deal with a particular level of the system at a time
 - Concerned with structure and function at each level

- Structure
 - The way in which components relate to each other
- Function
 - The operation of individual components as part of the structure



Function

There are four basic functions that a computer can perform:

- Data processing
 - Data may take a wide variety of forms and the range of processing requirements is broad
- Data storage
 - Short-term
 - Long-term
- Data movement
 - Input-output (I/O) when data are received from or delivered to a device (peripheral) that is directly connected to the computer
 - Data communications when data are moved over longer distances, to or from a remote device
- Control
 - A control unit manages the computer's resources and orchestrates the performance of its functional parts in response to instructions

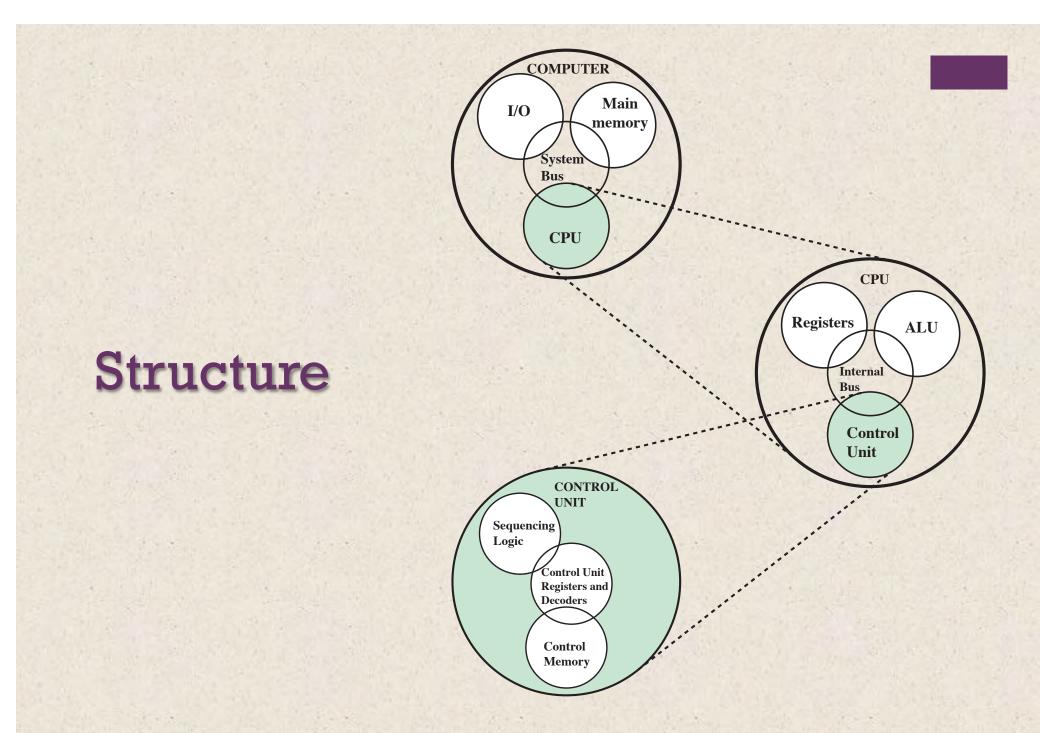
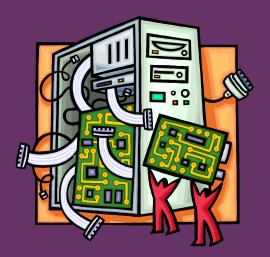


Figure 1.1 A Top-Down View of a Computer

There are four main structural components of the computer:



 CPU – controls the operation of the computer and performs its data processing functions

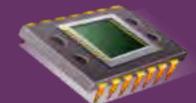
Main Memory – stores data

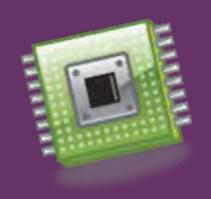
 I/O – moves data between the computer and its external environment

 System Interconnection – some mechanism that provides for communication among CPU, main memory, and I/O

CPU

Major structural components:





Control Unit

- Controls the operation of the CPU and hence the computer
- Arithmetic and Logic Unit (ALU)
 - Performs the computer's data processing function
- Registers
 - Provide storage internal to the CPU
- CPU Interconnection
 - Some mechanism that provides for communication among the control unit, ALU, and registers

Multicore Computer Structure

Central processing unit (CPU)

- Portion of the computer that fetches and executes instructions
- Consists of an ALU, a control unit, and registers
- Referred to as a processor in a system with a single processing unit

Core

- An individual processing unit on a processor chip
- May be equivalent in functionality to a CPU on a single-CPU system
- Specialized processing units are also referred to as cores

Processor

- A physical piece of silicon containing one or more cores
- Is the computer component that interprets and executes instructions
- Referred to as a *multicore processor* if it contains multiple cores

Cache Memory

 Multiple layers of memory between the processor and main memory

Is smaller and faster than main memory

Used to speed up memory access by placing in the cache data from main memory that is likely to be used in the near future

A greater performance improvement may be obtained by using multiple levels of cache, with level 1 (L1) closest to the core and additional levels (L2, L3, etc.) progressively farther from the core

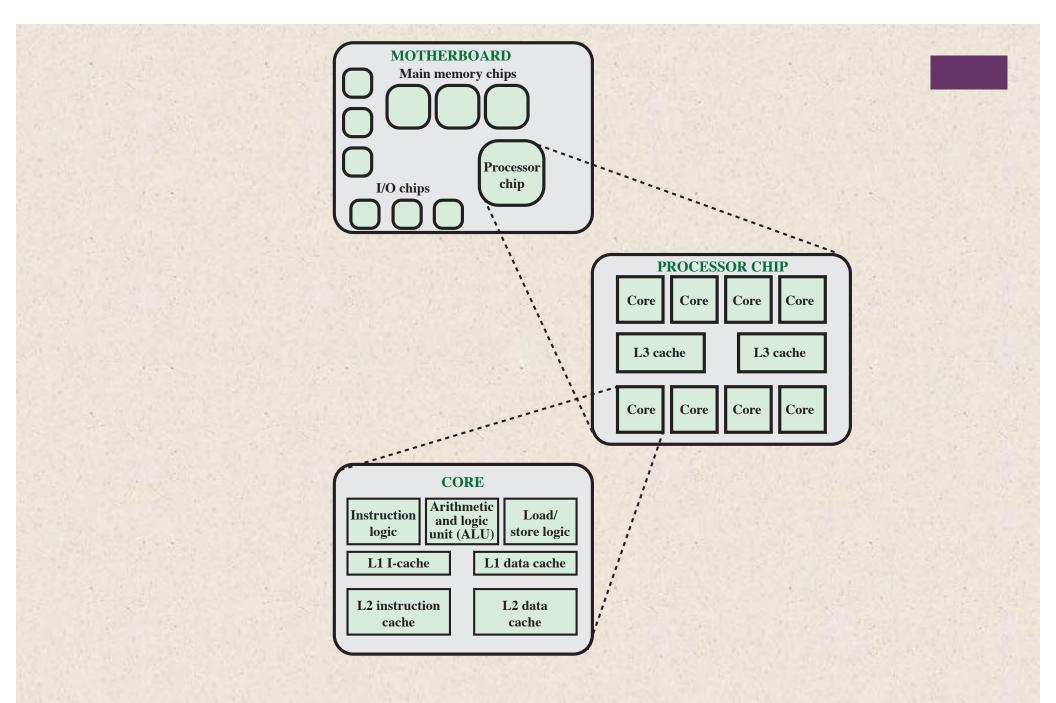


Figure 1.2 Simplified View of Major Elements of a Multicore Computer

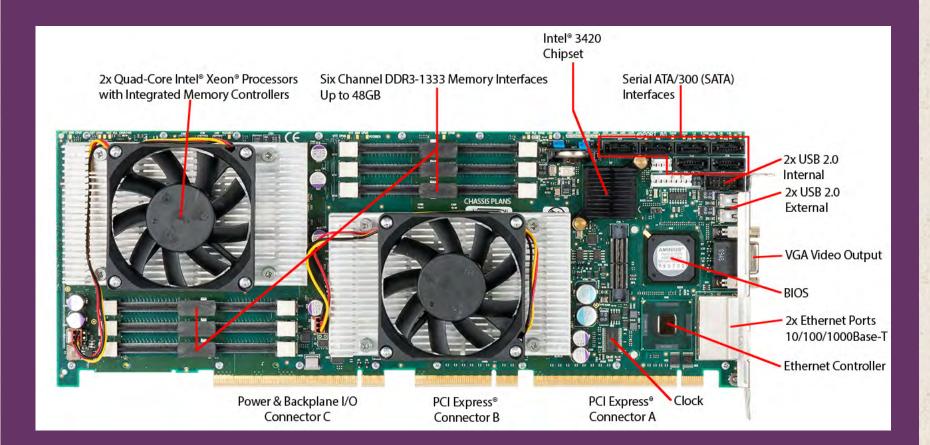


Figure 1.3 Motherboard with Two Intel Quad-Core Xeon Processors

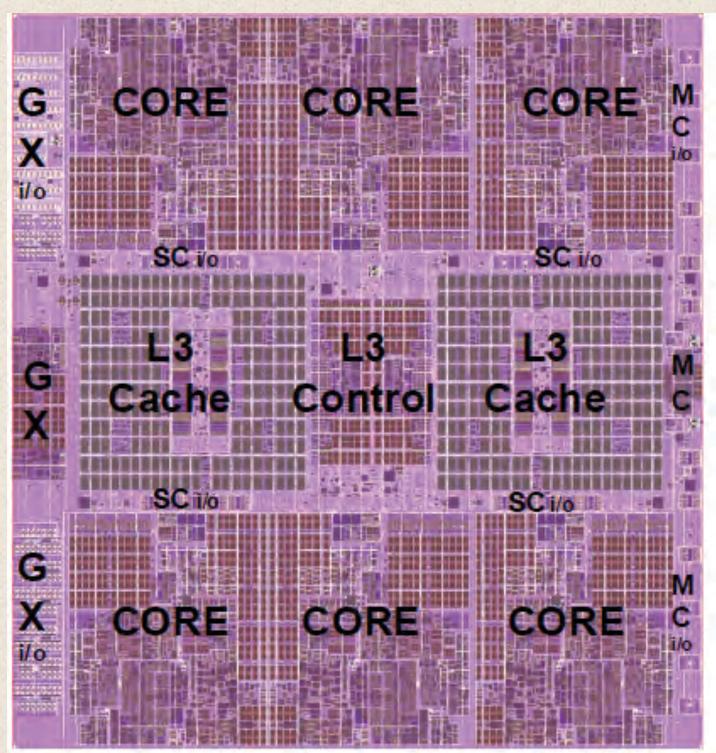


Figure 1.4

zEnterprise EC12 Processor Unit (PU) Chip Diagram

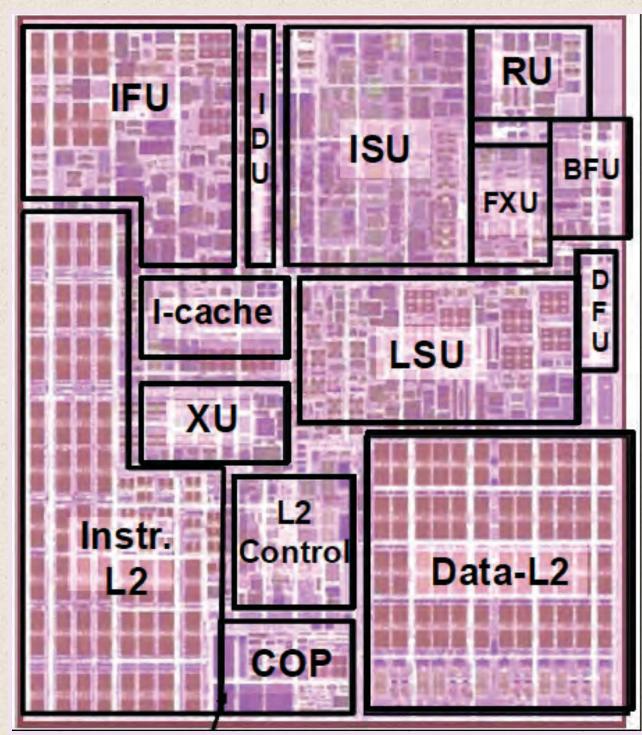


Figure 1.5

zEnterprise EC12 Core Layout

History of Computers First Generation: Vacuum Tubes

- Vacuum tubes were used for digital logic elements and memory
- IAS computer
 - Fundamental design approach was the stored program concept
 - Attributed to the mathematician John von Neumann
 - First publication of the idea was in 1945 for the EDVAC
 - Design began at the Princeton Institute for Advanced Studies
 - Completed in 1952
 - Prototype of all subsequent general-purpose computers

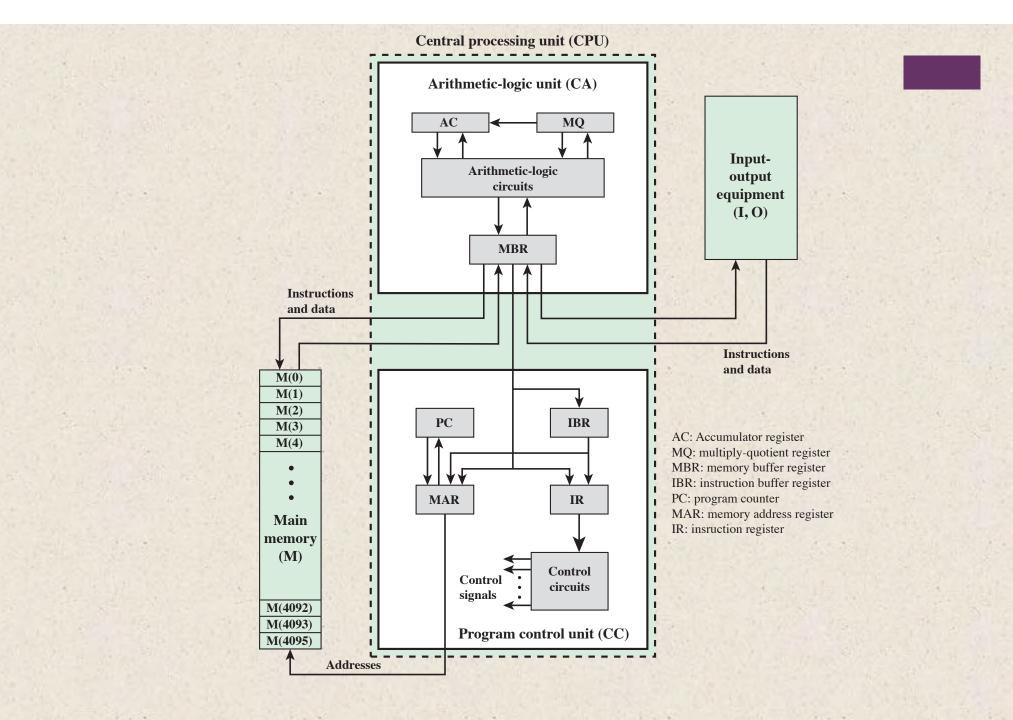


Figure 1.6 IAS Structure

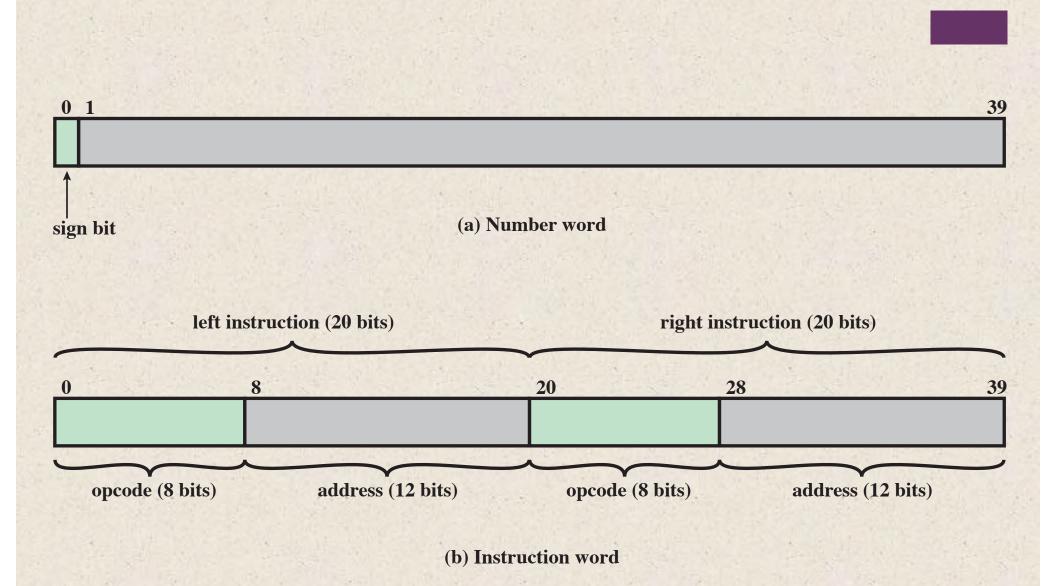
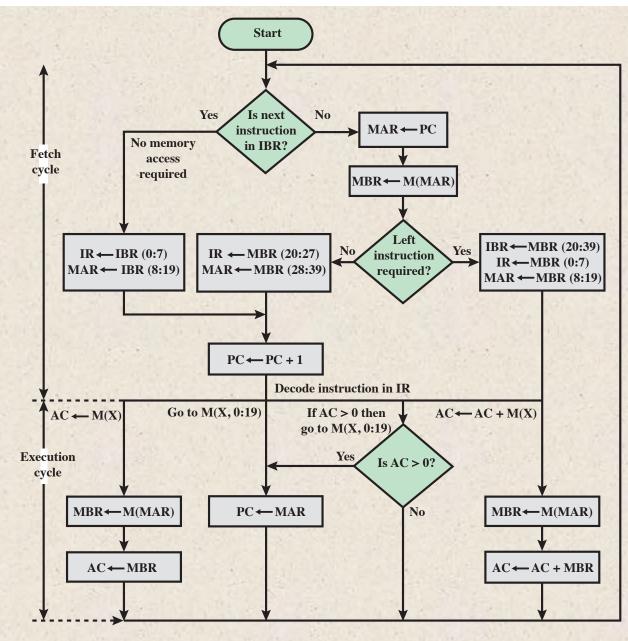


Figure 1.7 IAS Memory Formats

Registers

Memory buffer register (MBR)	 Contains a word to be stored in memory or sent to the I/O unit Or is used to receive a word from memory or from the I/O unit
Memory address register (MAR)	• Specifies the address in memory of the word to be written from or read into the MBR
Instruction register (IR)	• Contains the 8-bit opcode instruction being executed
Instruction buffer register (IBR)	• Employed to temporarily hold the right-hand instruction from a word in memory
Program counter (PC)	• Contains the address of the next instruction pair to be fetched from memory
Accumulator (AC) and multiplier quotient (MQ)	 Employed to temporarily hold operands and results of ALU operations



M(X) = contents of memory location whose address is X (i:j) = bits i through j

Figure 1.8 Partial Flowchart of IAS Operation

Instruction Type	Opcode	Symbolic Representation	Description	
	00001010	LOAD MQ	Transfer contents of register MQ to the accumulator AC	
Data transfer	00001001	LOAD MQ,M(X)	Transfer contents of memory location X to MQ	
	00100001	STOR M(X)	Transfer contents of accumulator to memory location X	
	00000001	LOAD M(X)	Transfer $M(X)$ to the accumulator	
	00000010	LOAD - M(X)	Transfer $-M(X)$ to the accumulator	
	00000011	LOAD M(X)	Transfer absolute value of $M(X)$ to the accumulator	
	00000100	LOAD - M(X)	Transfer $- M(X) $ to the accumulator	
Unconditional	00001101	JUMP M(X,0:19)	Take next instruction from left half of $M(X)$	
branch	00001110	JUMP M(X,20:39)	Take next instruction from right half of M(X)	
	00001111	JUMP+ M(X,0:19) JU	If number in the accumulator is nonnegative, take next instruction from left half of M(X) <i>If number in the</i>	
		MP	accumulator is nonnegative,	
Conditional branch		+	take next instruction from	
		M(X ,20:	right half of $M(X)$	
		,20. 39)		
	00000101	ADD M(X)	Add M(X) to AC; put the result in AC	
	00000111	ADD M(X)	Add $ M(X) $ to AC; put the result in AC	
	00000110	SUB M(X)	Subtract $M(X)$ from AC; put the result in AC	
Arithmetic	00001000	SUB M(X)	Subtract $ M(X) $ from AC; put the remainder in AC	
	00001011	MUL M(X)	Multiply M(X) by MQ; put most significant bits of result in AC, put least significant bits in MQ	
	00001100	DIV M(X)	Divide AC by M(X); put the quotient in MQ and the remainder in AC	
	00010100	LSH	Multiply accumulator by 2; i.e., shift left one bit position	
	00010101	RSH	Divide accumulator by 2; i.e., shift right one position	
Address modify	00010010	STOR M(X,8:19)	Replace left address field at M(X) by 12 rightmost bits of AC	
	00010011	STOR M(X,28:39)	Replace right address field at M(X) by 12	

Table 1.1

The IAS Instruction Set

(Table can be found on page 17 in the textbook.)

History of Computers Second Generation: Transistors

- Smaller
- Cheaper
- Dissipates less heat than a vacuum tube
- Is a solid state device made from silicon
- Was invented at Bell Labs in 1947
- It was not until the late 1950's that fully transistorized computers were commercially available



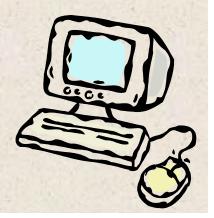
Table 1.2 Computer Generations

Generation	Approximate Dates	Technology	Typical Speed (operations per second)
1	1946–1957	Vacuum tube	40,000
2	1957–1964	Transistor	200,000
3	1965–1971	Small and medium scale integration	1,000,000
4	1972–1977	Large scale integration	10,000,000
5	1978–1991	Very large scale integration	100,000,000
6	1991-	Ultra large scale integration	>1,000,000,000

Second Generation Computers

Introduced:

- More complex arithmetic and logic units and control units
- The use of high-level programming languages
- Provision of system software which provided the ability to:
 - Load programs
 - Move data to peripherals
 - Libraries perform common computations



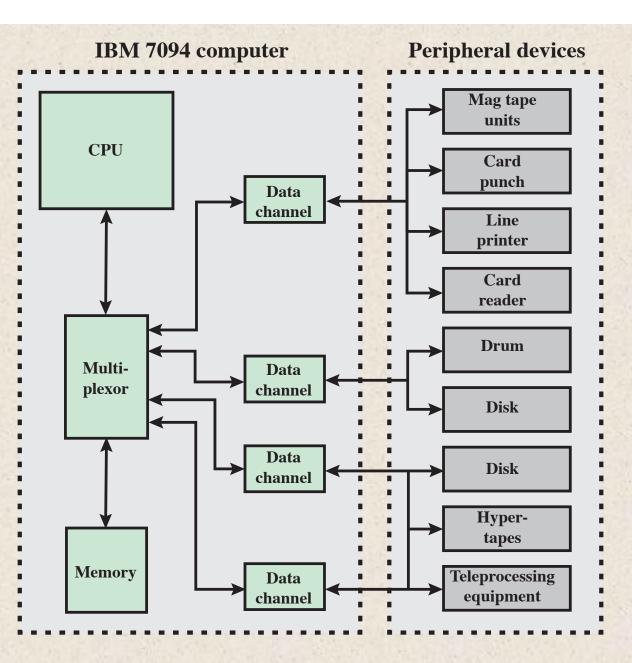
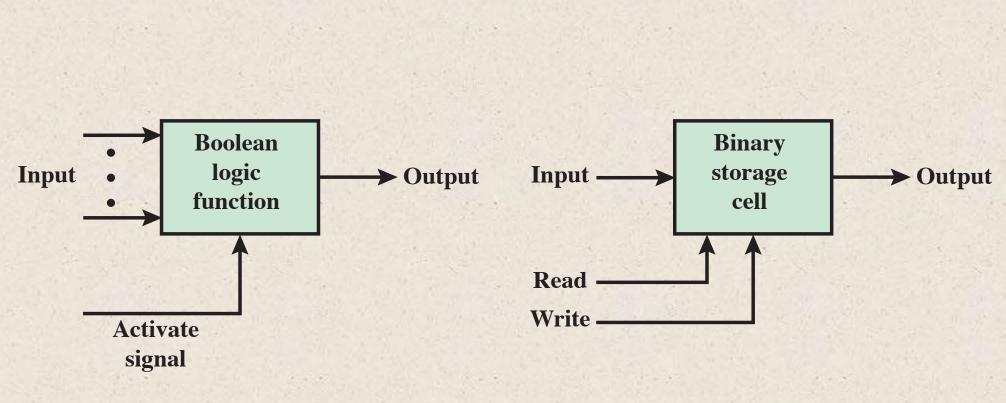


Figure 1.9 An IBM 7094 Configuration

History of Computers Third Generation: Integrated Circuits

- 1958 the invention of the integrated circuit
- Discrete component
 - Single, self-contained transistor
 - Manufactured separately, packaged in their own containers, and soldered or wired together onto masonite-like circuit boards
 - Manufacturing process was expensive and cumbersome
- The two most important members of the third generation were the IBM System/360 and the DEC PDP-8





(a) Gate

(b) Memory cell

Figure 1.10 Fundamental Computer Elements

Integrated Circuits

- Data storage provided by memory cells
- Data processing provided by gates
- Data movement the paths among components are used to move data from memory to memory and from memory through gates to memory
- Control the paths among components can carry control signals

- A computer consists of gates, memory cells, and interconnections among these elements
- The gates and memory cells are constructed of simple digital electronic components
- Exploits the fact that such components as transistors, resistors, and conductors can be fabricated from a semiconductor such as silicon
- Many transistors can be produced at the same time on a single wafer of silicon
- Transistors can be connected with a processor metallization to form circuits

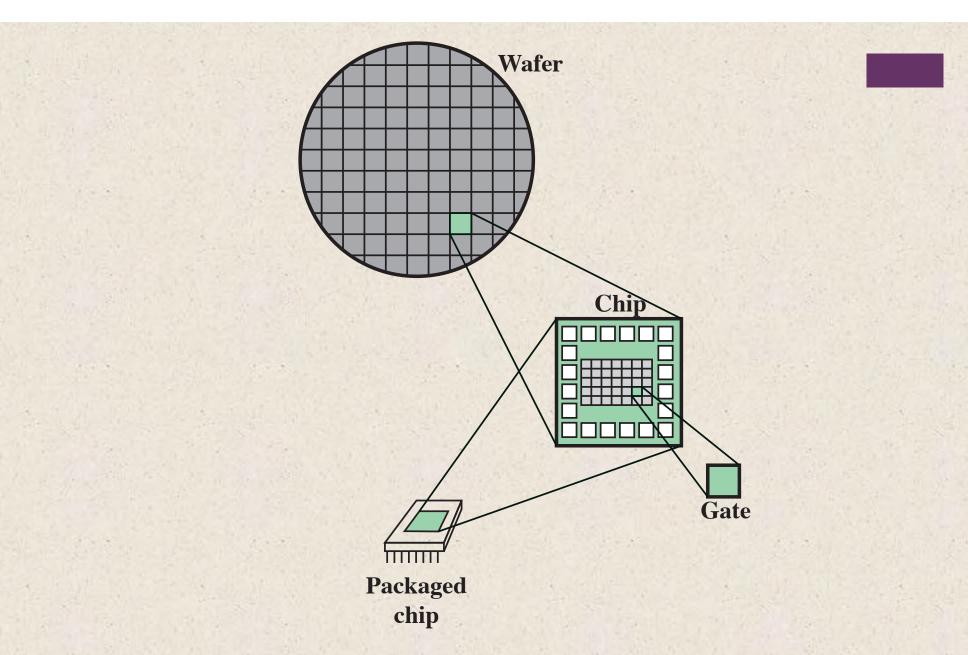


Figure 1.11 Relationship Among Wafer, Chip, and Gate

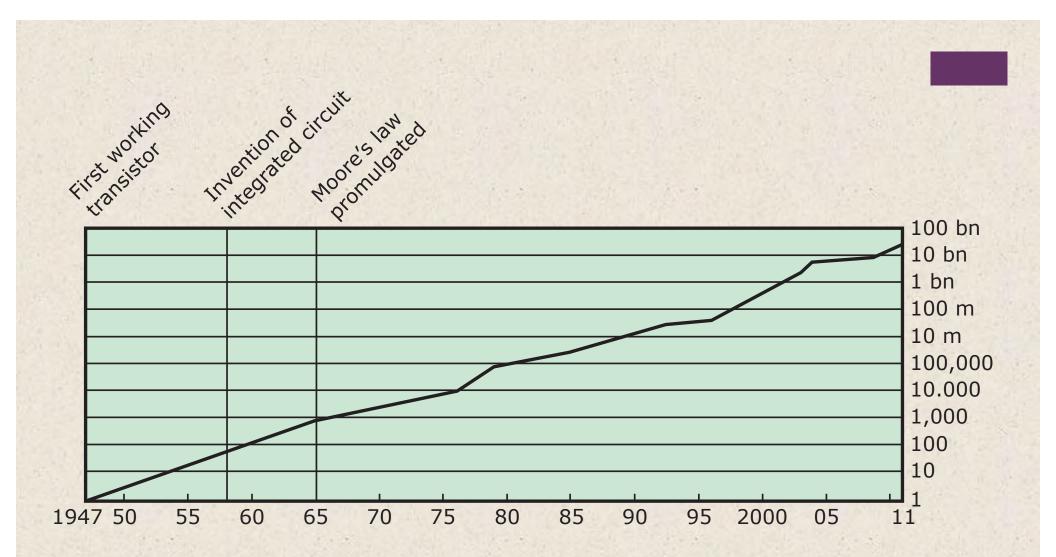
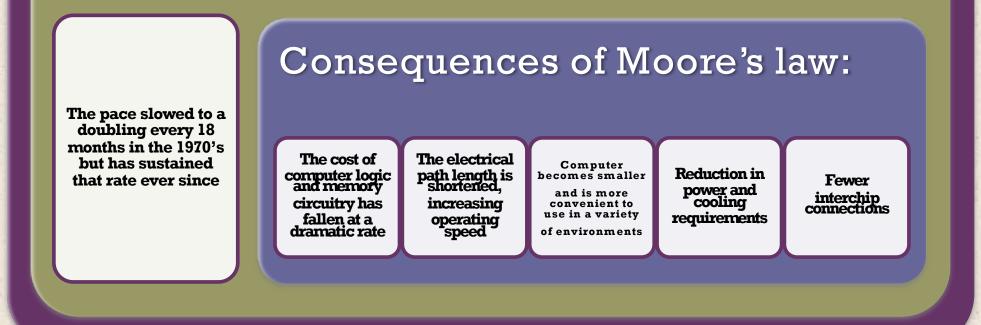


Figure 1.12 Growth in Transistor Count on Integrated Circuits (DRAM memory)

Moore's Law

1965; Gordon Moore – co-founder of Intel

Observed number of transistors that could be put on a single chip was doubling every year



IBM System/360

- Announced in 1964
- Product line was incompatible with older IBM machines
- Was the success of the decade and cemented IBM as the overwhelmingly dominant computer vendor
- The architecture remains to this day the architecture of IBM's mainframe computers
- Was the industry's first planned family of computers
 - Models were compatible in the sense that a program written for one model should be capable of being executed by another model in the series

+ Family Characteristics

Similar or identical instruction set Similar or identical operating system

Increasing speed Increasing number of I/O ports

Increasing memory size

Increasing cost

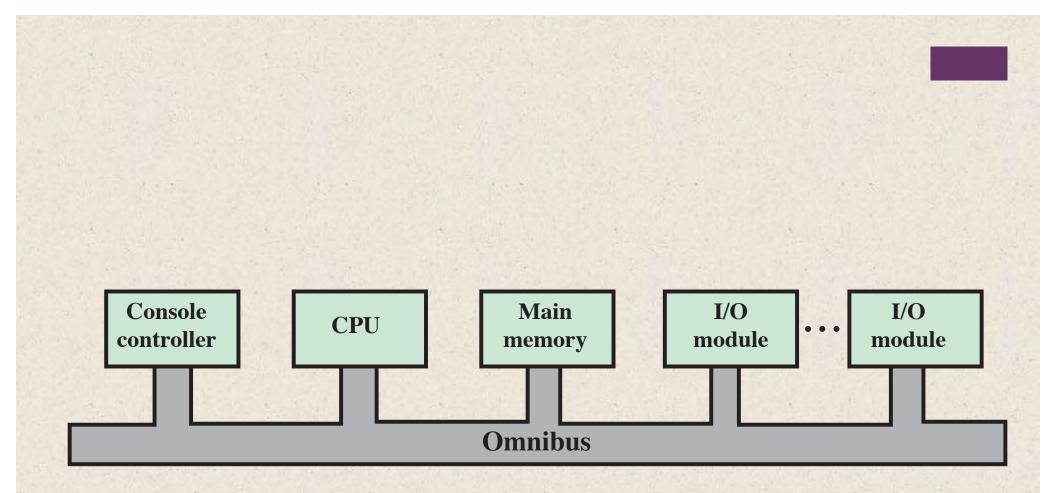


Figure 1.13 PDP-8 Bus Structure

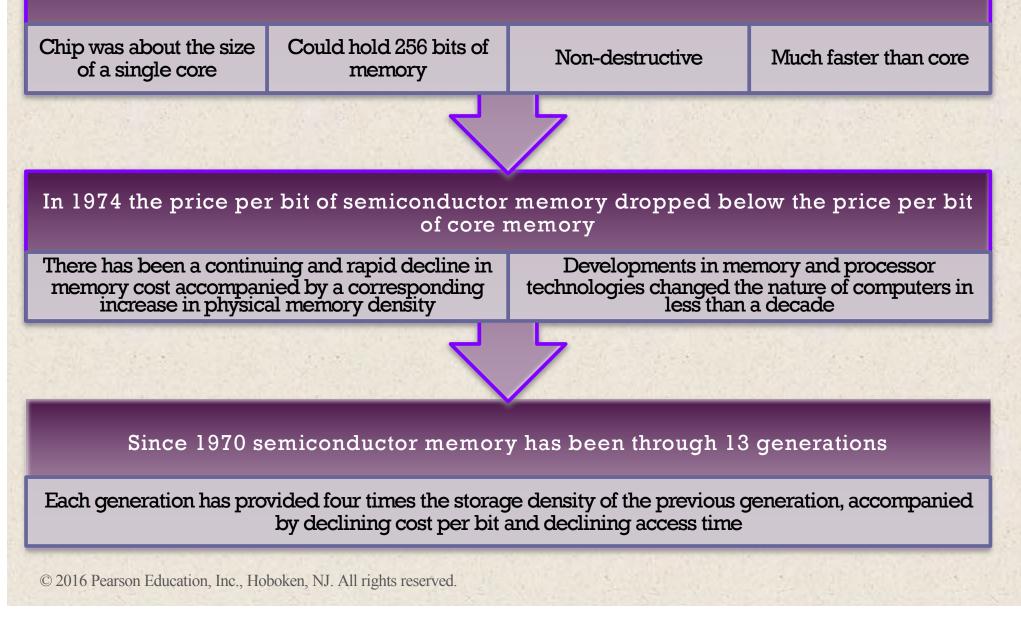
Later Generations

VLSI Very Large Scale Integration LSI Large Scale Integration

Semiconductor Memory Microprocessors ULSI Ultra Large Scale Integration

Semiconductor Memory

In 1970 Fairchild produced the first relatively capacious semiconductor memory



Microprocessors

The density of elements on processor chips continued to rise

 More and more elements were placed on each chip so that fewer and fewer chips were needed to construct a single computer processor

1971 Intel developed 4004

- First chip to contain all of the components of a CPU on a single chip
- Birth of microprocessor
- 1972 Intel developed 8008
 - First 8-bit microprocessor
- 1974 Intel developed 8080
 - First general purpose microprocessor
 - Faster, has a richer instruction set, has a large addressing capability





	4004	8008	8080	8086	8088
Introduced	1971	1972	1974	1978	1979
Clock speeds	108 kHz	108 kHz	2 MHz	5 MHz, 8 MHz, 10 MHz	5 MHz, 8 MHz
Bus width	4 bits	8 bits	8 bits	16 bits	8 bits
Number of transistors	2,300	3,500	6,000	29,000	29,000
Feature size (µm)	10	8	6	3	6
Addressable memory	640 Bytes	16 KB	64 KB	1 MB	1 MB

(a) 1970s Processors

	80286	386TM DX	386TM SX	486TM DX CPU
Introduced	1982	1985	1988	1989
Clock speeds	6 MHz - 12.5 MHz	16 MHz - 33 MHz	16 MHz - 33 MHz	25 MHz - 50 MHz
Bus width	16 bits	32 bits	16 bits	32 bits
Number of transistors	134,000	275,000	275,000	1.2 million
Feature size (µm)	1.5	1	1	0.8 - 1
Addressable memory	16 MB	4 GB	16 MB	4 GB
Virtual memory	1 GB	64 TB	64 TB	64 TB
Cache				8 kB

(b) 1980s Processors



	486TM SX	Pentium	Pentium Pro	Pentium II
Introduced	1991	1993	1995	1997
Clock speeds	16 MHz - 33	60 MHz - 166	150 MHz - 200	200 MHz - 300
	MHz	MHz,	MHz	MHz
Bus width	32 bits	32 bits	64 bits	64 bits
Number of	1.185 million	3.1 million	5.5 million	7.5 million
transistors	1.105 1111101	<i>5.1</i> mmion	5.5 mmon	7.5 11111011
Feature size (µm)	1	0.8	0.6	0.35
Addressable	4 GB	4 GB	64 GB	64 GB
memory			0100	0105
Virtual memory	64 TB	64 TB	64 TB	64 TB
Cache	8 kB	8 kB	512 kB L1 and 1	512 kB L2
Cuelle	0 KD	0 KD	MB L2	512 KD L2

(c) 1990s Processors

	Pentium III	Pentium 4	Core 2 Duo	Core i7 EE 4960X
Introduced	1999	2000	2006	2013
Clock speeds	450 - 660 MHz	1.3 - 1.8 GHz	1.06 - 1.2 GHz	4 GHz
Bus wid th	64 bits	64 bits	64 bits	64 bits
Number of transistors	9.5 million	42 million	167 million	1.86 billion
Feature size (nm)	250	180	65	22
Addressable memory	64 GB	64 GB	64 GB	64 GB
Virtual memory	64 TB	64 TB	64 TB	64 TB
Cache	512 kB L2	256 kB L2	2 MB L2	1.5 MB L2/15 MB L3
Number of cores	1	1	2	6

(d) Recent Processors

The Evolution of the Intel x86 Architecture

- Two processor families are the Intel x86 and the ARM architectures
- Current x86 offerings represent the results of decades of design effort on complex instruction set computers (CISCs)
- An alternative approach to processor design is the reduced instruction set computer (RISC)
- ARM architecture is used in a wide variety of embedded systems and is one of the most powerful and best-designed RISC-based systems on the market

Highlights of the Evolution of the Intel Product Line:

8080	8086	80286	80386	80486
 World's first general- purpose microprocessor 8-bit machine, 8-bit data path to memory Was used in the first personal computer (Altair) 	 A more powerful 16-bit machine Has an instruction cache, or queue, that prefetches a few instructions before they are executed The first appearance of the x86 architecture The 8088 was a variant of this processor and used in IBM's first personal computer (securing the success of Intel 	• Extension of the 8086 enabling addressing a 16-MB memory instead of just 1MB	 Intel's first 32- bit machine First Intel processor to support multitasking 	 Introduced the use of much more sophisticated and powerful cache technology and sophisticated instruction pipelining Also offered a built-in math coprocessor

Highlights of the Evolution of the Intel Product Line:

Pentium

• Intel introduced the use of superscalar techniques, which allow multiple instructions to execute in parallel

Pentium Pro

• Continued the move into superscalar organization with aggressive use of register renaming, branch prediction, data flow analysis, and speculative execution

Pentium II

• Incorporated Intel MMX technology, which is designed specifically to process video, audio, and graphics data efficiently

Pentium III

Incorporated additional floating-point instructions

•Streaming SIMD Extensions (SSE)

Pentium 4

• Includes additional floating-point and other enhancements for multimedia

Core

• First Intel x86 micro-core

Core 2

- Extends the Core architecture to 64 bits
- Core 2 Quad provides four cores on a single chip
- More recent Core offerings have up to 10 cores per chip
- An important addition to the architecture was the Advanced Vector Extensions instruction set

Embedded Systems

- The use of electronics and software within a product
- Billions of computer systems are produced each year that are embedded within larger devices
- Today many devices that use electric power have an embedded computing system
- Often embedded systems are tightly coupled to their environment
 - This can give rise to real-time constraints imposed by the need to interact with the environment
 - Constraints such as required speeds of motion, required precision of measurement, and required time durations, dictate the timing of software operations
 - If multiple activities must be managed simultaneously this imposes more complex real-time constraints



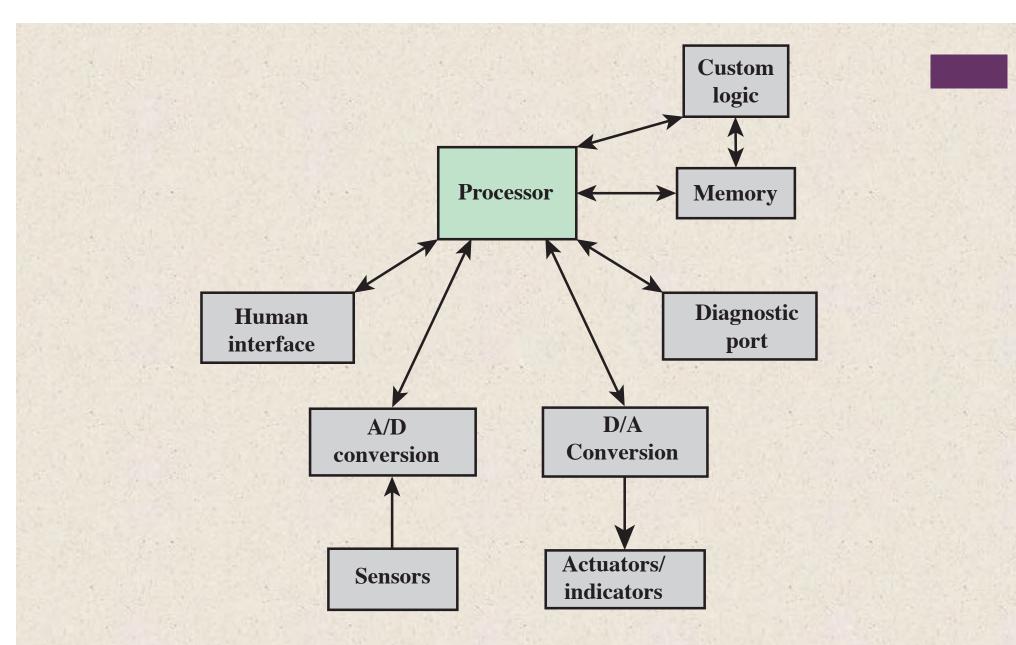


Figure 1.14 Possible Organization of an Embedded System

The Internet of Things (IoT)

- Term that refers to the expanding interconnection of smart devices, ranging from appliances to tiny sensors
- Is primarily driven by deeply embedded devices
- Generations of deployment culminating in the IoT:
 - Information technology (IT)
 - PCs, servers, routers, firewalls, and so on, bought as IT devices by enterprise IT people and primarily using wired connectivity
 - Operational technology (OT)
 - Machines/appliances with embedded IT built by non-IT companies, such as medical machinery, SCADA, process control, and kiosks, bought as appliances by enterprise OT people and primarily using wired connectivity
 - Personal technology
 - Smartphones, tablets, and eBook readers bought as IT devices by consumers exclusively using wireless connectivity and often multiple forms of wireless connectivity
 - Sensor/actuator technology
 - Single-purpose devices bought by consumers, IT, and OT people exclusively using wireless connectivity, generally of a single form, as part of larger systems
- It is the fourth generation that is usually thought of as the IoT and it is marked by the use of billions of embedded devices

Embedded Operating Systems

Application Processors versus Dedicated Processors

- There are two general approaches to developing an embedded operating system (OS):
 - Take an existing OS and adapt it for the embedded application
 - Design and implement an OS intended solely for embedded use

- Application processors
 - Defined by the processor's ability to execute complex operating systems
 - General-purpose in nature
 - An example is the smartphone the embedded system is designed to support numerous apps and perform a wide variety of functions
- Dedicated processor
 - Is dedicated to one or a small number of specific tasks required by the host device
 - Because such an embedded system is dedicated to a specific task or tasks, the processor and associated components can be engineered to reduce size and cost

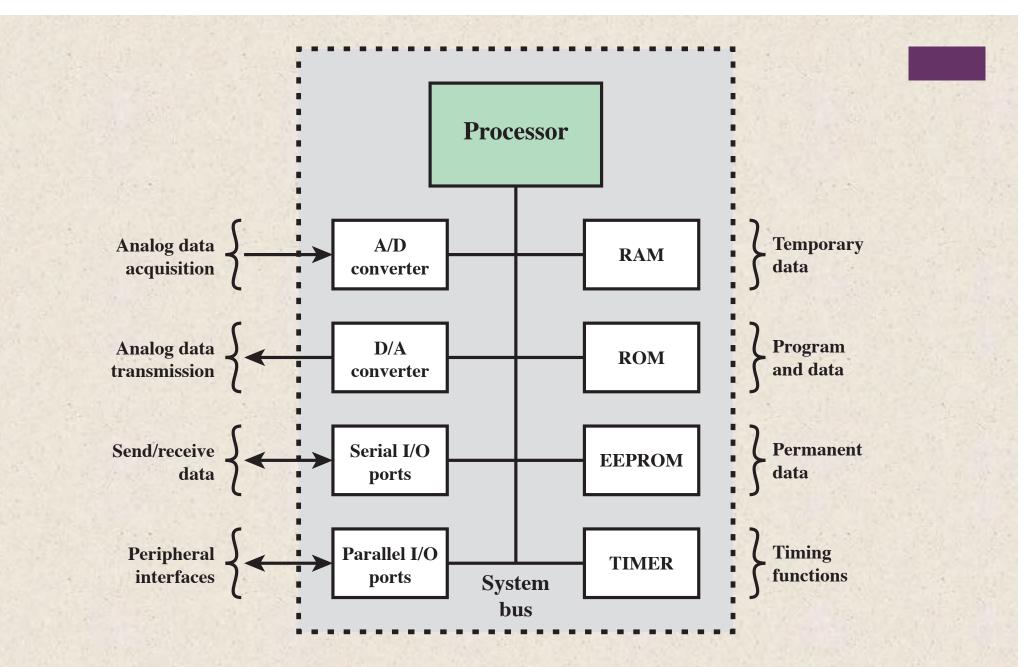


Figure 1.15 Typical Microcontroller Chip Elements

Deeply Embedded Systems

- Subset of embedded systems
- Has a processor whose behavior is difficult to observe both by the programmer and the user
- Uses a microcontroller rather than a microprocessor
- Is not programmable once the program logic for the device has been burned into ROM
- Has no interaction with a user
- Dedicated, single-purpose devices that detect something in the environment, perform a basic level of processing, and then do something with the results
- Often have wireless capability and appear in networked configurations, such as networks of sensors deployed over a large area
- Typically have extreme resource constraints in terms of memory, processor size, time, and power consumption



Refers to a processor architecture that has evolved from RISC design principles and is used in embedded systems

Family of RISC-based microprocessors and microcontrollers designed by ARM Holdings, Cambridge, England

Chips are high-speed processors that are known for their small die size and low power requirements

Probably the most widely used embedded processor architecture and indeed the most widely used processor architecture of any kind in the world

Acorn RISC Machine/Advanced RISC Machine

ARM Products

Cortex-R

Cortex-A/Cortex-A50

Cortex-M

- Cortex-M0
- Cortex-M0+
- Cortex-M3
- Cortex-M4

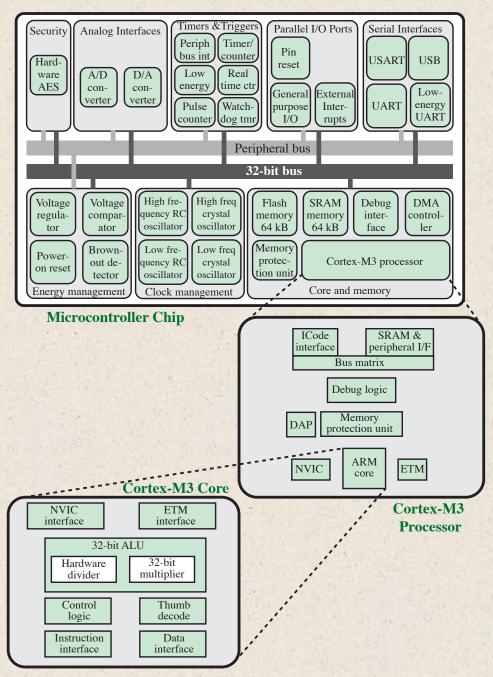


Figure 1.16 Typical Microcontroller Chip Based on Cortex-M3

Cloud Computing

NIST defines cloud computing as:

"A model for enabling ubiquitous, convenient, on-demand network access to a shared pool of configurable computing resources that can be rapidly provisioned and released with minimal management effort or service provider interaction."

- You get economies of scale, professional network management, and professional security management
- The individual or company only needs to pay for the storage capacity and services they need
- Cloud provider takes care of security

Cloud Networking

- Refers to the networks and network management functionality that must be in place to enable cloud computing
- One example is the provisioning of high-performance and/or highreliability networking between the provider and subscriber
- The collection of network capabilities required to access a cloud, including making use of specialized services over the Internet, linking enterprise data center to a cloud, and using firewalls and other network security devices at critical points to enforce access security policies

Cloud Storage

- Subset of cloud computing
- Consists of database storage and database applications hosted remotely on cloud servers
- Enables small businesses and individual users to take advantage of data storage that scales with their needs and to take advantage of a variety of database applications without having to buy, maintain, and manage the storage assets

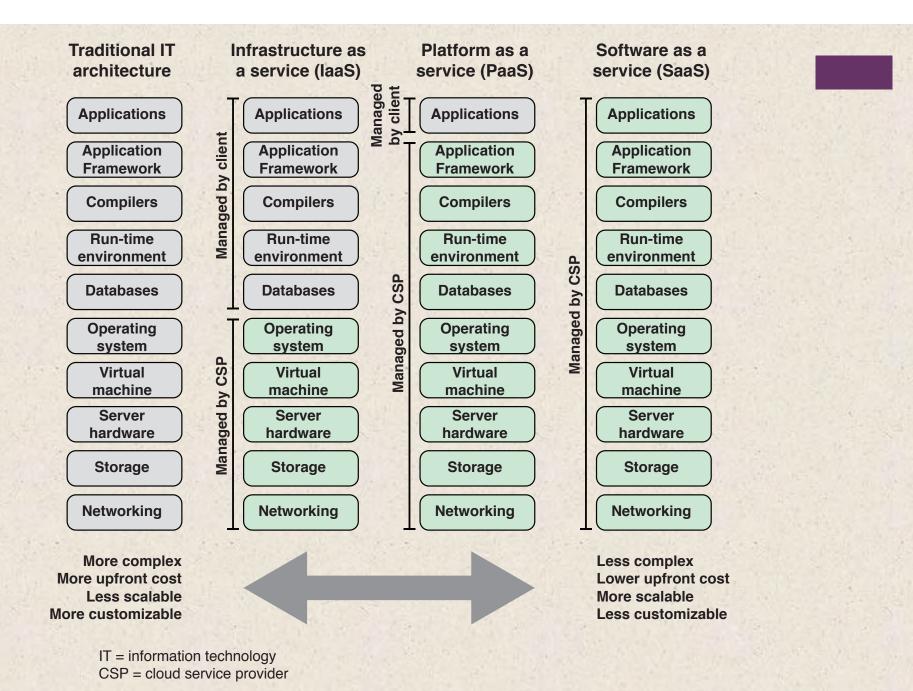


Figure 1.17 Alternative Information Technology Architectures

Summary

Chapter 1

- Organization and architecture
- Structure and function
- Brief history of computers
 - The First Generation: Vacuum tubes
 - The Second Generation: Transistors
 - The Third Generation: Integrated Circuits
 - Later generations
- The evolution of the Intel x86 architecture
- Cloud computing
 - Basic concepts
 - Cloud services

Basic Concepts and Computer Evolution

- Embedded systems
 - The Internet of things
 - Embedded operating systems
 - Application processors versus dedicated processors
 - Microprocessors versus microcontrollers
 - Embedded versus deeply embedded systems
- ARM architecture
 - ARM evolution
 - Instruction set architecture
 - ARM products